

A study on Thai exchange rate volatility model comparison: a nonparametric approach

Theepakorn Jithitkulchai (2005)

Agenda

- Introduction
 - Statement of problem
 - Objective
 - Scope of Study
- Introductory Nonparametric Econometrics
- Nonparametric Volatility Model
- Parametric Volatility Models
- Data and Descriptive Statistics
- Statistical Tests
- Empirical Results

Introduction

- Statement of problem
 - Basic assumption of conditional homoskedasticity is inappropriate
 - So the specification of a dynamic structure for conditional variance (heteroskedasticity) are introduced
 - There are ARCH, GARCH,... models estimated by NL-MLE
 - But sensitivity to model misspecification (ad hoc functional form determination)
 - Therefore, nonparametric econometrics is one of the solutions in corrective estimation

Introduction

- Objective
 - To study the differentiation of parametric and nonparametric estimation on exchange rate conditional volatility
 - To compare predictability performance among different approached competitive models

Introduction

- Scope of Study
 - Compare the nonparametric and parametric models prediction's performance
 - Volatility of weekly Baht/U.S. rate of return in 2000-2005
 - Rolling Mean squared prediction error (MSPE) as the measurement

Introductory Nonparametric Econometrics

- General Concept
 - Minimized set of assumptions
 - Minimum of structure imposed on the regression function
 - Only some degree of smoothness is necessary for nonparametric method
 - Continuity of function is enough to ensure the convergence of estimator as the size of data increases
 - Additional smoothness (existence of derivatives) allows more asymptotic efficient estimation

Introductory Nonparametric Econometrics

- Basic Model

$$y_t = m(x_t) + u_t \quad ; t = 1, \dots, T$$

$$u_t \sim i.i.d.(0, s^2)$$


$$\hat{m}(x) = \sum_{t=1}^T w_t(x) y_t \quad ; \sum_{t=1}^T w_t(x) = 1$$

“Weighted average” of y_t

Introductory Nonparametric Econometrics

■ Kernel Function

- Probability density function which is a piecewise continuous function, unimodal, integrating to one, symmetric about zero, and has first two moments finite

- The examples of the kernel functions are

- Uniform kernel:

$$K(z) = \frac{1}{2} I_{[-1,1]}(z)$$

- Standard normal kernel:

$$K(z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}z^2}; -\infty < z < \infty$$

- Epanechnikov kernel:

$$K(z) = \frac{3}{4}(1-z^2)I_{[-1,1]}(z)$$

- Quartic kernel:

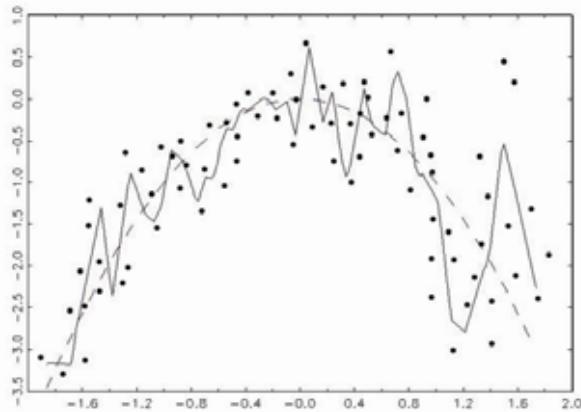
$$K(z) = \frac{15}{16}(1-z^2)^2 I_{[-1,1]}(z)$$

- As rolling windows to estimate curve at each sample point

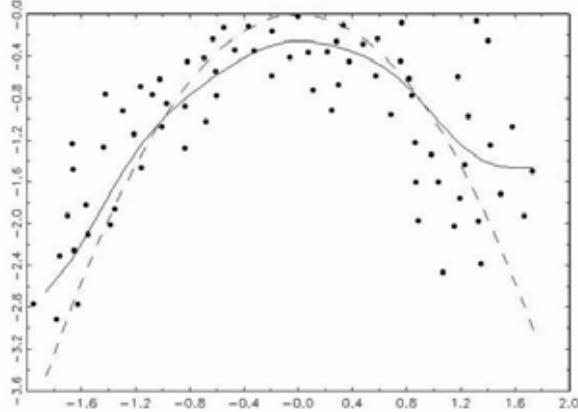
Introductory Nonparametric Econometrics

- Different Bandwidths for Nadaraya-Watson estimators

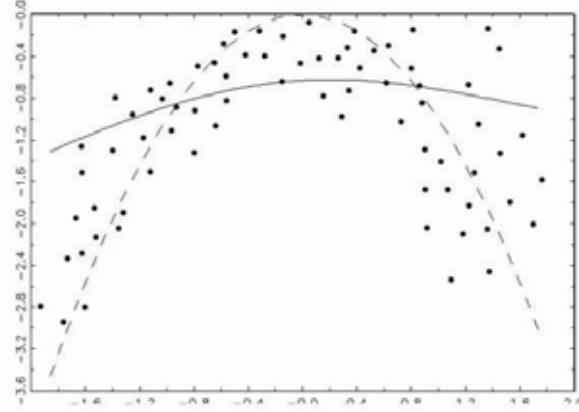
Bandwidth = 0.04



Bandwidth = 0.35



Bandwidth = 0.1



Introductory Nonparametric Econometrics

- Cross Validation Bandwidth
 - Optimal smoothing estimator
 - Automatic balancing the trade-off between biased and variance
(smaller bandwidth >> smaller bias but higher variance)

$$h^* \subseteq \arg \min CV(h) = \frac{1}{T} \sum_{t=1}^T (Y_t - \hat{m}_{-t}(X_t, h))^2$$

(Cross-Validation criterion)

; \hat{m}_{-t} = “leave-one-out” estimator

Introductory Nonparametric Econometrics

■ Local Constant Estimator

$$m(x) \subseteq \arg \min \sum_{t=1}^T \{Y_t - m\}^2 K\left(\frac{X_t - x}{h}\right)$$


$$\hat{m}(x) = \left(\sum_{t=1}^T K_t \right)^{-1} \sum_{t=1}^T K_t Y_t \quad ; K_t = K\left(\frac{X_t - x}{h}\right)$$

Matrix Notation:

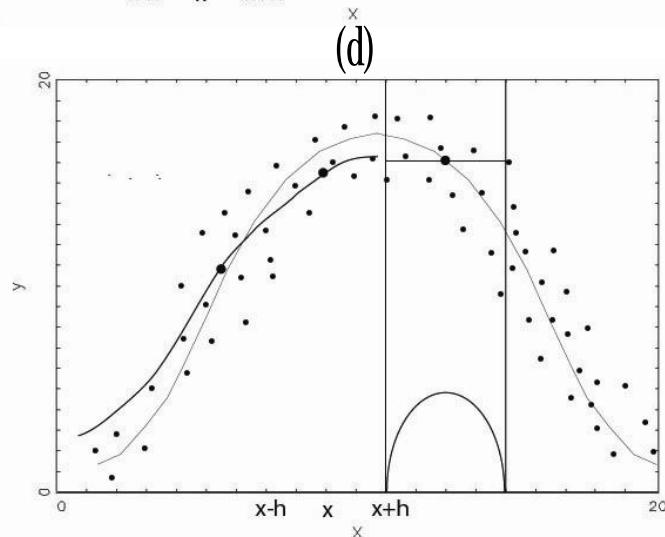
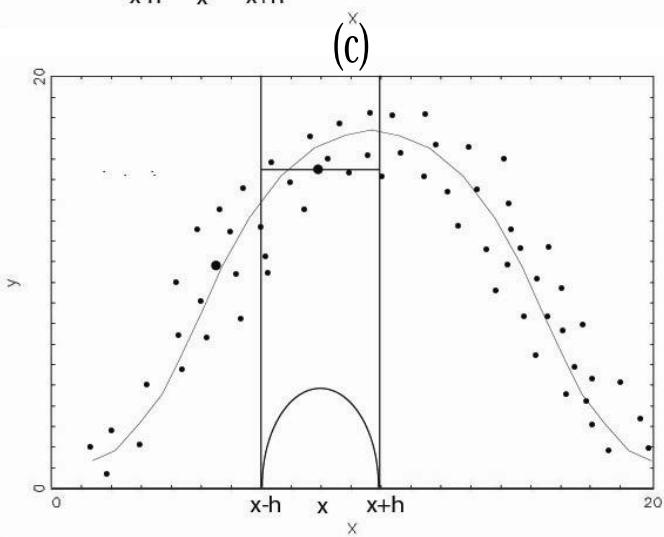
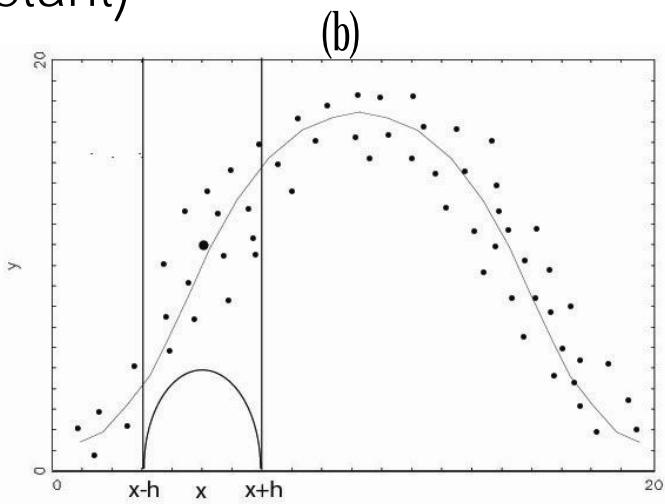
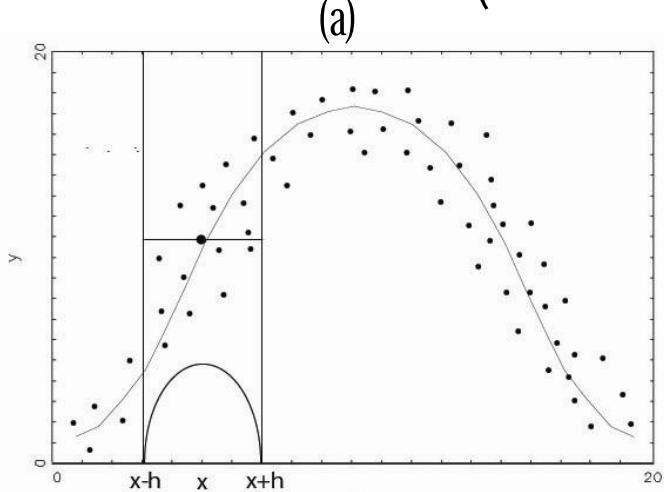
$$\min_{\{m\}} (Y - mi)' \Omega (Y - mi) \quad ; i = (1 \dots 1)', \quad \Omega = \text{diag}[K\left(\frac{X_t - x}{h}\right)]$$



$$\hat{m} = (i' \Omega i)^{-1} i' \Omega y \equiv \left(\sum_{t=1}^T K_t \right)^{-1} \sum_{t=1}^T K_t Y_t$$

Introductory Nonparametric Econometrics

- Data Driven Estimator (Local Constant)



Introductory Nonparametric Econometrics

■ Asymptotic Result of Local Constant Estimator

If x_1, \dots, x_T be i.i.d. observations with pdf $f(x)$ which are twice continuously differentiable, also the s^{th} order derivatives of $f(x)$, $f^{(s)}(x)$, $s = 0, 1, 2$, are bounded functions. And the kernel function $K(\cdot)$ satisfies

$$\text{(i)} \int K(z)dz = 1 \quad \text{(ii)} \int zK(z)dz = 0 \quad \text{(iii)} \int z^2 K(z)dz = k_2 > 0$$

If as $T \rightarrow \infty$, $h \rightarrow 0$ and $Th \rightarrow \infty$, where

$$\hat{f}(x) = (Th)^{-1} \sum_{t=1}^T K\left(\frac{X_t - x}{h}\right),$$

then $\boxed{\hat{f}(x) \rightarrow f(x)}$ in MSE



$$\hat{m}(x) \xrightarrow{P} m(x)$$

$$; y_t = m(x_t) + u_t = E(y_t | x_t) + u_t$$

Introductory Nonparametric Econometrics

■ Local Linear Estimator

$$m(x) \subseteq \arg \min_{\{m\}} \sum_{t=1}^T \{Y_t - m - (X_t - x)' \beta\}^2 K\left(\frac{X_t - x}{h}\right)$$

→ $\hat{\delta}(x) = (\hat{m}(x), \hat{\beta}(x)')'$; $\beta(x) = \partial m(x) / \partial x$

Matrix Notation:

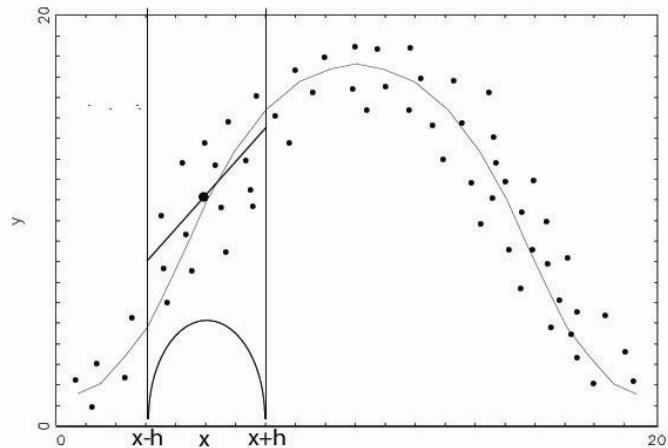
$$\min_{\{m, \beta\}} (Y - \chi \delta)' \Omega (Y - \chi \delta) ; \Omega = diag[K\left(\frac{X_t - x}{h}\right)]$$

→ $\hat{\delta}(x) = (\chi' \Omega \chi)^{-1} \chi' \Omega y$

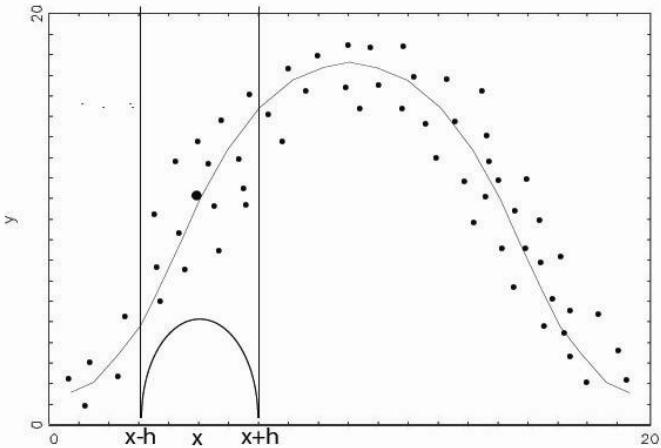
Introductory Nonparametric Econometrics

- Data Driven Estimator (Local Linear)

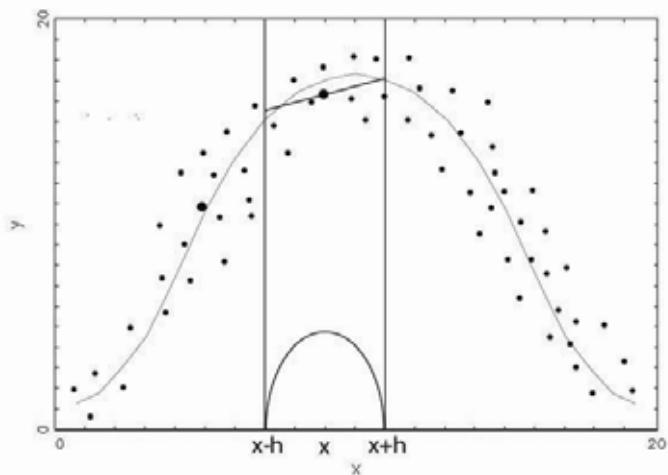
(a)



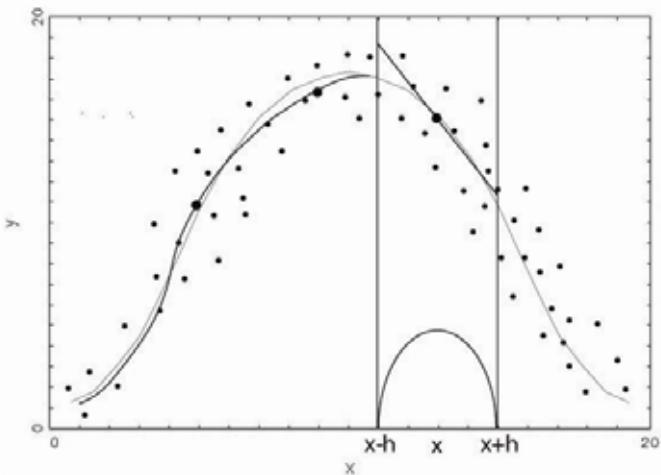
(b)



(c)



(d)



Introductory Nonparametric Econometrics

■ Asymptotic Result of Local Linear Estimator

Given assumptions

(i) $(X_t, Y_t)_{t=1}^T \sim i.i.d.$; $X_t \in \mathbb{R}^p$. Both X_t and $u_t = Y_t - m - (X_t - x)' \beta$ have finite fourth moment

(ii) $m(x)$ is twice differentiable, and its second order derivative is bounded.

$\sigma^2(x) = E(u^2 | X = x)$ is continuous in x

and (iii) K is a second order kernel, as $T \rightarrow \infty$, $h \rightarrow 0$, and $Th^{p+2} \rightarrow \infty$. Also assumes that K is a compact supported bounded function, such that $K > 0$ on a set of positive Lebesgue measure, then

$$\Rightarrow \hat{\delta}(x) \xrightarrow{P} \delta(x)$$

Nonparametric Volatility Model

- Generalization for any time series smoothed conditional mean and conditional variance functions

$$y_t = m(y_{t-1}) + \sigma(y_{t-1})u_t \quad ; u_t \sim i.i.d.(0,1)$$

$$\begin{aligned}\sigma^2(x) &= E((Y_t - m(x))^2 | Y_{t-1} = x) \\ &= E(Y_t^2 | Y_{t-1} = x) - (E(Y_t | Y_{t-1} = x))^2\end{aligned}$$

→ $\hat{\sigma}^2(x) = \hat{g}(x) - \hat{m}^2(x) \quad ; m(x) = E(Y_t | Y_{t-1} = x)$
 $g(x) = E(Y_t^2 | Y_{t-1} = x)$

Parametric Volatility Models

- Autoregressive Conditional Heteroskedasticity Processes

ARCH: $\sigma_t^2 = \zeta + \alpha u_{t-1}^2$

GARCH: $\sigma_t^2 = \zeta + \alpha u_{t-1}^2 + \beta u_{t-1}^2$

I-GARCH: $\sigma_t^2 = \zeta + \alpha u_{t-1}^2 + \beta u_{t-1}^2 ; \alpha + \beta = 1$

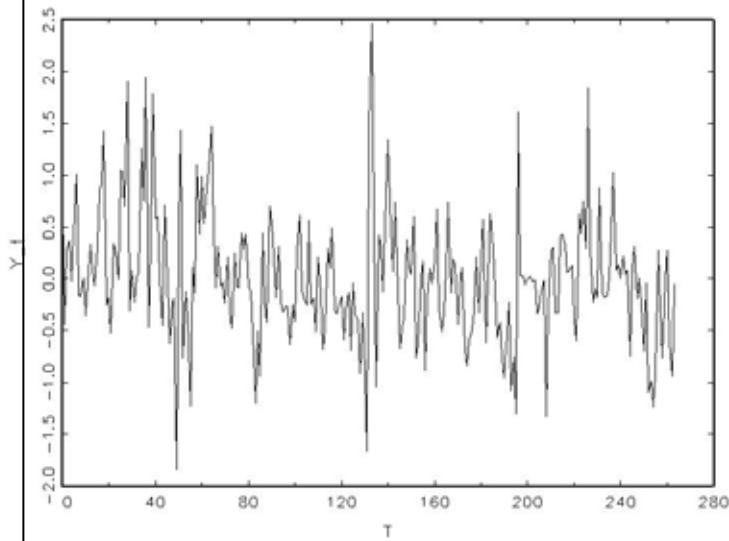
EGARCH: $\ln \sigma_t^2 = \omega + \delta \ln \sigma_{t-1}^2 + \alpha |u_{t-1}| / \sigma_{t-1} + \gamma(u_{t-1} / \sigma_{t-1})$

TGARCH: $\sigma_t^2 = \kappa + \alpha u_{t-1}^2 + \beta u_{t-1}^2 d_{t-1} + \delta \sigma_{t-1}^2 ; d_t = 1 (u_t < 0) \text{ or } 0 (\text{otherwise})$

ARCH-M : $\sigma_t^2 = \zeta + \alpha u_{t-1}^2 ; Y_t = Y_{t-1}' \beta + \xi \sigma_t^2 + u_t$

Data and Descriptive Statistics

Weekly Baht/U.S. Return (264 observations)

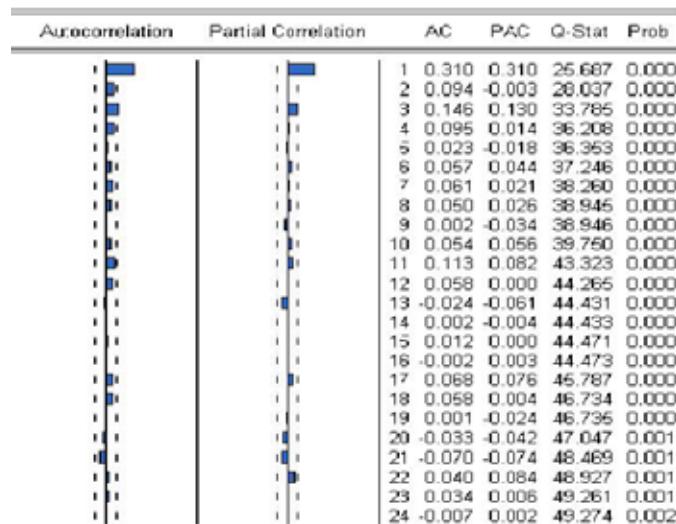


Descriptive Statistics

Mean	0.012550
Median	-0.044315
Maximum	2.463100
Minimum	-1.845640
Std. Dev.	0.624152
Skewness	0.561577
Kurtosis	4.478065
Jarque-Bera	37.90766
Probability	0.000000

Number of observations = 265

ACF and PACF functions



Statistical Tests

OLS AR(1) and its statistics

$$Y_t = 0.3104 Y_{t-1}$$

s.d. = (0.078640)

p-value = [0.000051]

$$Y_t = 0.310179 + 0.000059 Y_{t-1}$$

s.d. = (0.000366) (0.058688)

p-value = [0.8721] [0.000000]

Unit Root test and ARCH-LM test

Unit Root Test	Statistic	Probability
Augmented Dickey-Fuller t-test	-12.14690	0.000000
Test Critical Values :	1% level 5% level	-3.993335 -3.427004

ARCH Test	Statistic	Probability
T*R-squared	14.56590	0.000135
F-statistic	15.30563	0.000117

Empirical Results

- For in-sample estimation and test of unbiasedness, there are no supports to indicate the favor between nonparametric and parametric models
- For out-of-sample performance, there is inconclusive evidence to justify whether nonparametric model outperform parametric models to forecast return
- However, predictive efficiency measured by rolling MSPE can find grounds for choosing nonparametric model to forecast volatility
- An asymmetric U-shaped "smiling face" form of the nonparametric volatility function is found.